

# FlexBotNDT

## **PROBLEM/ISSUE ADDRESSED**

Automation of the NDT scanning process for large parts – Relieving operators of the tiresome, time consuming and monotonous work – allowing him/ her to focus on data interpretation

## **SOLUTION**

Human Robot Collaborative (HRC) system that can accurately perform the delicate scanning process and be programmed interactively to accommodate multiple part types.

## **WHY IT IS IMPORTANT FOR SOCIETY**

Collaborative robots provide physical assistance and enhanced operator work environment. They are able to:

- increase the attractiveness of the job and promote the wellbeing of the manufacturing personnel.
- increase accessibility of the job since the demanding part is handled by a robot and the worker can focus on interpreting the acquired data.

“ Thanks to EIT we were able to bring together the right competences to automate a traditionally manual, costly and difficult process... ”



## **MAIN RESULTS & INSIGHTS**



HRC system and custom NDT end effector integrating scanning probe and coupling media application



• Intuitive programming interface optimized for human robot interaction



• 3D radar system for safe human detection and HR collaboration



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### **MAIN PRODUCT**

FlexBotNDT project

**AIM:** Flexible non-destructive-testing using collaborative robots



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